

Tutorials 4.1 Attitude

De Wiki

Aller à : [navigation](#), [rechercher](#)

[Tutorials 4.1 Attitude](#)

Sommaire

- [1 Attitude](#)
- [2 Attitude laws](#)
- [3 Attitude legs](#)
- [4 Attitude sequence](#)

Attitude

We must not confuse an [Attitude](#) and an [AttitudeLaw](#) (or [AttitudeLawLeg](#)). Indeed an [Attitude](#) is the current orientation of the spacecraft as the other ones will define the "laws" allowing to determine at each moment, the [Attitude](#).

For example, if we have an inertial [AttitudeLaw](#), the (inertial) [Attitude](#) of the spacecraft will be the same at each moment of the trajectory.

But if we have a Sun Pointing [AttitudeLaw](#), the current [Attitude](#) will change at each step.

So, most of the time, users will define [AttitudeLaw](#) or [AttitudeLawLeg](#) and will get the current [Attitude](#) using the [getAttitude\(\)](#) method.

Attitude laws

Building an attitude law is relatively easy, using one of the the constructors available depending of the kind of law you want to use. Next examples show different cases.

Code examples:

- [create a LOF attitude law](#)
- [create a Solar pointed attitude law](#)
- [create a two directions attitude law](#)

Attitude legs

To be written ...

Attitude sequence

[AttitudesSequence](#) is a very powerful concept which allows to define attitude logic all along a mission. Indeed, as it is based on orbital events detection, it avoids to define step by step attitude laws. For example, if we want to have:

- [LVLH](#) attitude during eclipse

- Sun pointing attitude else

... only two "switches" inside the attitude sequence are sufficient. It is coded in the proposed following tutorial.

Code example: [create a sequence of attitude laws](#)

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[Catégorie](#) :

- [Tutorials 4.1](#)

Menu de navigation

Outils personnels

- [3.136.19.203](#)
- [Discussion avec cette adresse IP](#)
- [Créer un compte](#)
- [Se connecter](#)

Espaces de noms

- [Page](#)
- [Discussion](#)

Variantes

Affichages

- [Lire](#)
- [Voir le texte source](#)
- [Historique](#)
- [Exporter en PDF](#)

Plus

Rechercher

PATRIUS

- [Welcome](#)

Evolutions

- [Main differences between V4.15 and V4.14](#)
- [Main differences between V4.14 and V4.13](#)
- [Main differences between V4.13 and V4.12](#)
- [Main differences between V4.12 and V4.11](#)
- [Main differences between V4.11 and V4.10](#)
- [Main differences between V4.10 and V4.9](#)
- [Main differences between V4.9 and V4.8](#)
- [Main differences between V4.8 and V4.7](#)
- [Main differences between V4.7 and V4.6.1](#)
- [Main differences between V4.6.1 and V4.5.1](#)
- [Main differences between V4.5.1 and V4.4](#)
- [Main differences between V4.4 and V4.3](#)
- [Main differences between V4.3 and V4.2](#)
- [Main differences between V4.2 and V4.1.1](#)
- [Main differences between V4.1.1 and V4.1](#)
- [Main differences between V4.1 and V4.0](#)
- [Main differences between V4.0 and V3.4.1](#)

User Manual

- [User Manual 4.15](#)
- [User Manual 4.14](#)
- [User Manual 4.13](#)
- [User Manual 4.12](#)
- [User Manual 4.11](#)
- [User Manual 4.10](#)
- [User Manual 4.9](#)
- [User Manual 4.8](#)
- [User Manual 4.7](#)
- [User Manual 4.6.1](#)
- [User Manual 4.5.1](#)
- [User Manual 4.4](#)
- [User Manual 4.3](#)
- [User Manual 4.2](#)
- [User Manual 4.1](#)
- [User Manual 4.0](#)
- [User Manual 3.4.1](#)
- [User Manual 3.3](#)

Tutorials

- [Tutorials 4.15](#)

- [Tutorials 4.14](#)
- [Tutorials 4.13.5](#)
- [Tutorials 4.12.1](#)
- [Tutorials 4.8.1](#)
- [Tutorials 4.5.1](#)
- [Tutorials 4.4](#)
- [Tutorials 4.1](#)
- [Tutorials 4.0](#)

Links

- [CNES freeware server](#)

Navigation

- [Accueil](#)
- [Modifications récentes](#)
- [Page au hasard](#)
- [Aide](#)

Outils

- [Pages liées](#)
- [Suivi des pages liées](#)
- [Pages spéciales](#)
- [Adresse de cette version](#)
- [Information sur la page](#)
- [Citer cette page](#)

• Dernière modification de cette page le 20 décembre 2018 à 15:37.

- [Politique de confidentialité](#)
- [À propos de Wiki](#)
- [Avertissements](#)

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