User Manual 4.13 Multi Propagation

De Wiki

Aller à : ,

User Manual 4.13 Multi Propagation

Sommaire

Introduction

Scope

This section describes the multi propagator provided by the Patrius library. At this time, only numerical propagator is available for multi spacecraft propagation. Generic features about propagators as well as other type of propagators are detailed [ORB_PGEN_Home here].

Javadoc

All the classes related to numerical propagation are in the `fr.cnes.sirius.patrius.propagation.numerical.multi` package of the Patrius library. The classes related to events detection are in the package `fr.cnes.sirius.patrius.propagation.events.multi` of the Patrius library. But the interface for multi event detectors is in `fr.cnes.sirius.patrius.propagation.events.multi` package of the Patrius library. All the classes related to attitude providers for multi satellites are in the package `fr.cnes.sirius.patrius.attitudes.multi`.

Library	Javadoc
Patrius	[Package fr.cnes.sirius.patrius.propagation.events.multi](#)
Patrius	[Package fr.cnes.sirius.patrius.events.multi](#)
Patrius	[Package fr.cnes.sirius.patrius.propagation.events.multi](#)
Patrius	[Package fr.cnes.sirius.patrius.propagation.numerical.multi](#)
Patrius	[Package fr.cnes.sirius.patrius.propagation.precomputed.multi](#)
Patrius	[Package fr.cnes.sirius.patrius.propagation.sampling.multi](#)
Patrius	[Package fr.cnes.sirius.patrius.attitudes.multi](#)

Links

Other useful links can be found here :

- [ORB_PRO_Home Classical propagation chapter]
- [FDY_SST_Home SpacecraftState chapter]

Useful Documents

None as of now.

Package Overview

Multi Numerical Propagator

The multi propagator architecture is copied from [Propagator](#) interface and [NumericalPropagator](#) class, and added to PATRIUS library.

Three propagation modes

Like single spacecraft propagation, the multi spacecraft propagation can be performed in different propagation modes : slave, master and ephemeris generation.

Features Description

The PATRIUS library offers a [multi numerical propagator](#). It aims at propagating several [SpacecraftState](#) at the same time using numerical propagation. The N [SpacecraftState](#) are propagated during the same time interval using the same [FirstOrderIntegrator](#).

Each state is identified with an ID of type String. All states can be completely different but they should have the same internal date.

As for the mono-satellite numerical propagation, it is possible to define the following global propagation parameters:

- The type of orbital parameters and position angle
- The propagation mode

For each state, it is possible to configure the following elements:

- The central attraction coefficient

- The force models
- The tolerances used for orbital parameters and the tolerances applied on additional states.
- The additional states equations associated with the additional states
- The attitude providers

It is possible to define event detectors applied on a specific state or global event detectors applied on several states.

Note that the NumericalPropagator and the MultiNumericalPropagator do not use anymore the Newtonian gravity model by default. It should now be added manually to the list of the force models before starting the propagation.

Getting started

Here is presented a basic instanciation of the multi numerical propagator.

Create propagator from FirstOrderIntegrator

The [MultiNumericalPropagator](#) should be created by giving a [FirstOrderIntegrator](#).

```
final MultiNumericalPropagator propagator = new
MultiNumericalPropagator(integrator);
```

The integrator could be declared using absolute and relative tolerances represented by :

- a scalar value

```
final double abstolScal = 1.0e-10;
final double reltolScal = 1.0e-10;
final FirstOrderIntegrator integratorScal = new
DormandPrince853Integrator(0.001, 200, abstolScal, reltolScal);
```

- a vector

```
final double[] abstolVec = { 1e-5, 1e-5, 1e-5, 1e-8, 1e-8, 1e-8};
final double[] reltolVec = { 1e-10, 1e-10, 1e-10, 1e-10, 1e-10, 1e-10};
final FirstOrderIntegrator integratorVec = new
DormandPrince853Integrator(0.1, 60., abstolVec, reltolVec);
```

The orbit tolerances (vector or scalar tolerances) given to the integrator are used as default tolerances. The orbit tolerances could be defined in vector type using the method ***setOrbitTolerance***.

Add initial states

Initial states could be added to the propagator using the method ***addInitialState(SpacecraftState, String)***. Each added state is defined by a unique ID. An error is raised if :

- the input spacecraft ID is empty or null.
- a state with the same ID was already added to the propagator.
- the date associated with the added state is different from the date associated with the states

previously added. (All states are propagated from the same date).

Note that, the initial state should be added before adding an additional equation, an attitude provider, a force model, an event ... etc ... associated with this state. Otherwise, the input spacecraft Id will not be recognized.

The map of the added states could be retrieved with ***getInitialStates()***

Add additional equations

As for the [NumericalPropagator](#), additional equations corresponding to the additional states of each states can be added to the propagator.

These additional equations are given to the multi numerical propagator for a specific state thanks to the following methods :

- ***addAdditionalEquation(AdditionalEquation, String)***
- ***addAttitudeEquation(AttitudeEquation, String)***
- ***setMassProviderEquation(MassProvider, String)*** (This method should be called only once, mass provider must be mass provider used in force models)

The method ***setAdditionalStateTolerance(String, double[], double[])*** may be used to add variation tolerance values (absolute and relative) to a specific additional state.

For each state, the additional states should correspond with the added additional equations (same name, same size). As of PATRIUS 4.13, partial derivatives equations are available for multi-numerical propagation with the class `MultiPartialDerivativesEquations`. They are used exactly the same way as for mono-satellite propagation. Note that a set of partial derivatives equations has to be provided for each satellite, allowing for different sets of partial derivatives equations for each satellite.

See [ORB_PRO_UseP mono numerical propagation] chapter for more details.

The following example shows how to propagate two basic SpacecraftState :

```
// Initial date
final AbsoluteDate date = AbsoluteDate.J2000_EPOCH;

// Constants
final double mu = Constants.EGM96_EARTH_MU;
final Frame gcrf = FramesFactory.getGCRF();
final String STATE1 = "STATE1";
final String STATE2 = "STATE2";
final String BODY = "body";

// First initial state
final Orbit orbit1 = new KeplerianOrbit(7500000, 0.001, 0.40, 0, 0,
0,PositionAngle.MEAN, gcrf, date, mu);
final MassProvider massModel = new SimpleMassModel(1000., BODY);
final SpacecraftState state1 = new SpacecraftState(orbit1, massModel);

// Second initial state
```

```
final Vector3D position = new Vector3D(7.0e6, 1.0e6, 4.0e6);
final Vector3D velocity = new Vector3D(-500.0, 8000.0, 1000.0);
final Orbit orbit2 = new EquinoctialOrbit(new PVCoordinates(position,
velocity), gcrf, date, mu);
final AttitudeProvider law = new
ConstantAttitudeLaw(FramesFactory.getEME2000(), Rotation.IDENTITY);
final Attitude attitude = law.getAttitude(orbit2, date, gcrf);
final SpacecraftState state2 = new SpacecraftState(orbit2, attitude);

// Add initial states to the propagator
propagator.addInitialState(state1, STATE1);
propagator.addInitialState(state2, STATE2);

// Note that the NumericalPropagator and the MultiNumericalPropagator do not
use anymore the Newtonian gravity model by default. It should now be added
manually to the list of the force models before starting the propagation.
mainPropagator.addForceModel(new DirectBodyAttraction(new
NewtonianGravityModel(mu, STATE1));
mainPropagator.addForceModel(new DirectBodyAttraction(new
NewtonianGravityModel(mu, STATE2));

// Add additional equation associated with the mass model of the first state
// Mass provider must be mass provider used in force models.
propagator.setMassProviderEquation(massModel, STATE1);
propagator.setAdditionalStateTolerance("MASS_" + BODY, new double[]{1e-7},
new double[]{1e-7}, STATE1);

// Set attitude provider associated with the second state
propagator.setAttitudeProvider(law, STATE2);

// propagation
final Map<String, SpacecraftState> finalStates =
propagator.propagate(date.shiftedBy(propagationDuration));
```

Propagate the attitude

As for the [NumericalPropagator](#), to propagate the [Attitude](#) of a specific state, two treatments could be applied :

- compute the attitude with an [AttitudeProvider](#) : ***setAttitudeProvider(AttitudeProvider, String)***.
  It is possible to deals with :
  - a single attitude by calling ***setAttitudeProvider(AttitudeProvider, String)***
  - two attitudes by calling ***setAttitudeProviderForces(AttitudeProvider, String)*** or
    setAttitudeProviderEvents(AttitudeProvider, String). It is not possible to call
    setAttitudeProvider(AttitudeProvider, String) and
    setAttitudeProviderForces(AttitudeProvider, String) (or
    setAttitudeProviderEvents(AttitudeProvider, String))
- propagate the attitude as a 7-dimension additional state :
  addAttitudeEquation(AttitudeEquation, String).
  In practical terms, the user has to build the additional equation by extending the abstract class
  [AttitudeEquation](#), call ***addAttitudeEquation(AttitudeEquation, String)***.

See [ORB_PRO_UseP mono numerical propagation] chapter for more details.

Add force model

For each state, a force model could be added to the list of forces used at each step by the propagator.

```
propagator.addForceModel(model, STATE1);
```

See [ORB_PHY_Home force model] chapter for more details.

Add event detector

The user could add :

- an [EventDetector](#) associated with a specific state using ***addEventDetector(EventDetector, String)***
- a [MultiEventDetector](#) associated with several states added to the propagator using ***addEventDetector(MultiEventDetector)***

See [MIS_EVT_Home events presentation] and [MIS_MEVEN_Home multi events presentation] chapters for more details.

Add attitude provider

The user could add :

- an [AttitudeProvider](#) returning the independant attitude of one satellite using ***setAttitudeProvider(AttitudeProvider, String)***
- a [MultiAttitudeProvider](#) returning the attitude of one satellite correlated to the other using ***setAttitudeProvider(MultiAttitudeProvider, String)***

Note that method `getAttitudeProvider()` always returns a `MultiAttitudeProvider` whether you provided a single or multi attitude provider. If you provided a single `AttitudeProvider` then you can retrive it by calling `((MultiAttitudeProviderWrapper) multiNumericalPropagator.getAttitudeProvider()).getAttitudeProvider()`

Contents

Interfaces

Interface	Summary	Javadoc
**MultiPropagator	This interface provides a way to propagate several states at any time.	[...](#)
**MultiAttitudeProvider	This interface is an attitude provider taking into account the state of the others satellites.	[...](#)
**MultiModeHandler	Common interface for all multi propagator mode handlers initialization.	[...](#)

Classes

Class	Summary	Javadoc
SpacecraftState	This class is the representation of a complete state holding orbit, attitude for forces and for events computation and additional states at a given date.	[...](#)
MultiNumericalPropagator	This class propagates several SpacecraftState using numerical integration.	[...](#)
AttitudeEquation	This class represents attitude differential equations.	[...](#)
MultiIntegratedEphemeris	This class stores sequentially generated orbital parameters for later retrieval.	[...](#)
MultiPartialDerivativesEquations	This class computes the partial derivatives equations for one satellite. It is handled exactly as its mono-satellite counterpart PartialDerivativesEquations.	[...](#)

Récupérée de
« http://patrius.cnes.fr/index.php?title=User_Manual_4.13_Multi_Propagation&oldid=3554 »
[Catégorie](#) :

- [User Manual 4.13 Orbit Propagation](#)

Rechercher

PATRIUS

- [Welcome](#)

Evolutions

- [Main differences between V4.15 and V4.14](#)
- [Main differences between V4.14 and V4.13](#)
- [Main differences between V4.13 and V4.12](#)
- [Main differences between V4.12 and V4.11](#)
- [Main differences between V4.11 and V4.10](#)
- [Main differences between V4.10 and V4.9](#)
- [Main differences between V4.9 and V4.8](#)
- [Main differences between V4.8 and V4.7](#)
- [Main differences between V4.7 and V4.6.1](#)
- [Main differences between V4.6.1 and V4.5.1](#)
- [Main differences between V4.5.1 and V4.4](#)
- [Main differences between V4.4 and V4.3](#)
- [Main differences between V4.3 and V4.2](#)
- [Main differences between V4.2 and V4.1.1](#)
- [Main differences between V4.1.1 and V4.1](#)
- [Main differences between V4.1 and V4.0](#)
- [Main differences between V4.0 and V3.4.1](#)

User Manual

- [User Manual 4.15](#)
- [User Manual 4.14](#)
- [User Manual 4.13](#)
- [User Manual 4.12](#)
- [User Manual 4.11](#)
- [User Manual 4.10](#)
- [User Manual 4.9](#)
- [User Manual 4.8](#)
- [User Manual 4.7](#)
- [User Manual 4.6.1](#)
- [User Manual 4.5.1](#)
- [User Manual 4.4](#)
- [User Manual 4.3](#)
- [User Manual 4.2](#)
- [User Manual 4.1](#)
- [User Manual 4.0](#)

- [User Manual 3.4.1](#)
- [User Manual 3.3](#)

Tutorials

- [Tutorials 4.15](#)
- [Tutorials 4.14](#)
- [Tutorials 4.13.5](#)
- [Tutorials 4.12.1](#)
- [Tutorials 4.8.1](#)
- [Tutorials 4.5.1](#)
- [Tutorials 4.4](#)
- [Tutorials 4.1](#)
- [Tutorials 4.0](#)

Links

- [CNES freeware server](#)

Navigation

- [Accueil](#)
- [Modifications récentes](#)
- [Page au hasard](#)
- [Aide](#)

Outils

- [Pages liées](#)
- [Suivi des pages liées](#)
- [Pages spéciales](#)
- [Adresse de cette version](#)
- [Information sur la page](#)
- [Citer cette page](#)