

User Manual 4.14 Multi events detection

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Introduction

Scope

Here are presented all the multi events detectors that could be used in multi propagation.

Javadoc

Those event detectors are available in the packages :

Library

Javadoc

Patrius [Package fr.cnes.sirius.patrius.propagation.event](#)

Patrius [Package fr.cnes.sirius.patrius.events](#)

Links

See :

- [ORB_MPRO_Home Multi propagation chapter]
- [MIS_EVT_Home Events detection introduction chapter]

Useful Documents

None as of now.

Package Overview

None as of now.

Features Description

Multi events detectors

The following events detectors could be used in mono and multi spacecraft propagation :

- [ThreeBodiesAngleDetector](#)
- [ExtremaThreeBodiesAngleDetector](#)
- [SatToSatMutualVisibilityDetector](#)

These three detectors extends [AbstractDetector](#) and implements [MultiEventDetector](#).

Using [multi numerical propagator](#), all states concerned by the detection are recovered from the global state vector.

Using one of the [mono propagator](#) (analytical or numerical), the main state is recovered from the propagation. The others states concerned by the detection are recovered from a `PVCoordinatesProvider`.

The meaning of the g switching function for the concerned event detectors, and their particularities are presented in dedicated chapter :

- [MIS_ORB_Home Orbit determination events chapter]for [ThreeBodiesAngleDetector](#) and [ExtremaThreeBodiesAngleDetector](#)
- [MIS_STASAT_Home Ground stations and satellites events] for [SatToSatMutualVisibilityDetector](#)

Getting Started

In multi numerical propagation case, the states concerned by the detection are identified with their ID. Specific constructors should be used in multi numerical propagation case.

These constructors take as parameter the ID of states concerned by the detection.

Here after is presented the instantiation of a `SatToSatMutualVisibilityDetector` in multi propagation case :

```
// Initialize multi numerical propagator
final FirstOrderIntegrator integratorMultiSat = new
DormandPrince853Integrator(.1, 60, 1e-9, 1e-9);
MultiNumericalPropagator mainPropagator = new
MultiNumericalPropagator(integratorMultiSat);
mainPropagator.addInitialState(mainState, STATE1);
mainPropagator.addInitialState(secondaryState, STATE2);
mainPropagator.setAttitudeProvider(attitudeProv, STATE1);
mainPropagator.setAttitudeProvider(attitudeProv, STATE2);
```

```
// Note that the NumericalPropagator and the MultiNumericalPropagator do not
use anymore the Newtonian gravity model by default. It should now be added
manually to the list of the force models before starting the propagation.
```

```
mainPropagator.addForceModel(new DirectBodyAttraction(new
NewtonianGravityModel(mainState.getMu(), STATE1));
mainPropagator.addForceModel(new DirectBodyAttraction(new
NewtonianGravityModel(secondaryState.getMu(), STATE2));
```

```

// Create SatToSatMutualVisibilityDetector
final MultiEventDetector detector = new
SatToSatMutualVisibilityDetector(STATE1, STATE2, mainSpacecraftSensorModel1,
secondarySpacecraftSensorModel2, false, 0.01, 10.e-10);

// Add detector
mainPropagator.addEventDetector(detector1);

// propagate
Map<String, SpacecraftState> endStates =
mainPropagator.propagate(date.shiftedBy(duration));

```

If a wrong constructor is used, i.e a constructor for mono propagation, an exception will be raised during propagation.

Contents

Interfaces

Interface	Summary	Javadoc
EventDetector	This interface represents an event finder.	EventDetector
MultiEventDetector	This interface represents an event finder in multi propagation case.	MultiEventDetector

Classes

Class	Summary	Javadoc
ThreeBodiesAngleDetector	This class handles events representing the reaching of a predetermined angle between three bodies.	ThreeBodiesAngleDetector
ExtremaThreeBodiesAngleDetector	This class handles events representing the reaching of of extrema for the angle between three bodies.	ExtremaThreeBodiesAngleDetector
SatToSatMutualVisibilityDetector	This class handles events representing the mutual visibility between two spacecraft's sensors.	SatToSatMutualVisibilityDetector

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