

# User Manual 4.1 SpacecraftState

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## Introduction

### Scope

This section describes the SpacecraftState object.

### Javadoc

The object [SpacecraftState](#) is available in the package `fr.cnes.sirius.patrius.propagation`.

### Links

Here is only described the SpacecraftState structure. Please refer to [ORB\_PRO\_Home propagation chapter].

### Useful Documents

None as of now.

### Overview

The [SpacecraftState](#) is composed of :

- an [orbit](#)
- an [attitude for forces computation](#)
- an [attitude for events computation](#)
- a map of additional states (including mass states added from [MassProvider](#)).

Two attitudes are stored in order to apply (if needed) a different treatment to each attitude.

## Features Description

### One orbit

The [SpacecraftState](#) is composed of one [Orbit](#). It is possible to simply declare a SpacecraftState with an orbit : `final SpacecraftState state = new SpacecraftState(orbit);`

The orbit could be updated using the following method : `final SpacecraftState newState = state.updateOrbit(newOrbit);` The attitude and additional states will remain the same and a new SpacecraftState will be created.

### Two attitudes

The user can use one single

[Attitude](#) or two different [Attitude](#) objects : one for forces computation and one for events computation. The following constructor can be used :

```
final SpacecraftState state = new SpacecraftState(orbit, attitudeForces, attitudeEvents);
```

It is possible to get the attitude for forces or events computation using the following methods:

```
final Attitude attForces = state.getAttitudeForces();
final Attitude attEvents = state.getAttitudeEvents();
```

The user can deal with a single attitude in the SpacecraftState using the following constructor:

```
final SpacecraftState state = new SpacecraftState(orbit, attitude);
final Attitude att = state.getAttitude();
```

If the following constructor is used, both attitudes are set to null value: `final SpacecraftState state = new SpacecraftState(orbit);` Then calling `getAttitude` or `getAttitudeForces` or `getAttitudeEvents` will return null attitude.

## Additional states

The additional states are stored in the SpacecraftState using a Map with the additional states names as keys. The additional states are in the type `double[]`. The additional states map could be given directly to the constructor as follow :

```
Map<String, double[]> addStates = new HashMap<String, double[]>();
addStates.put("name", new double[]{1.0});
SpacecraftState state = new SpacecraftState(orbit, attitudeForces, attitudeEvents, addStates);
```

It is possible to add an additional state to a SpacecraftState using ***addAdditionalState***:

```
state2 = state.addAdditionalState("name2", new double[]{0.1, 0.1});
```

Note ***addAdditionalState*** returns a new SpacecraftState with the added additional state. It is necessary to store the returned object. The additional state is not added to the current state.

## Mass

A [MassProvider](#) can be provided to the SpacecraftState. In that case, the mass information are automatically stored as additional states. Be careful, the mass values can never be negative:

```
final SpacecraftState state = new SpacecraftState(orbit, massProvider);
final SpacecraftState state = new SpacecraftState(orbit, attitudeForces, attitudeEvents, massProvider, addStates);
```

The mass provider can be added to the SpacecraftState after its initialisation with the method

addMassProvider :

```
final SpacecraftState state = new SpacecraftState(orbit);  
final SpacecraftState newState = state.addMassProvider(massProvider);
```

The mass parts from MassProvider are added to additional states map with the key :  
"MASS\_<partName>".

The total mass of the SpacecraftState could not be obtained.

It is possible to obtain the mass of a given part : `state.getMass("part1");`

and to update the mass of a given part : `state.updateMass("part1", 1000.0);`

## State vector

The [SpacecraftState](#) object could be created from a state vector : `final SpacecraftState state = new SpacecraftState(stateVector, OrbitType.CARTESIAN, PositionAngle.MEAN, date, mu, frame, addStatesInfo, attProviderForces, attProviderEvents);`

To build the SpacecraftState, it is necessary to know the size and the index of all additional states in the state vector. This information could be obtained from an old state using the following method :

```
final Map<String, AdditionalStateInfo> addStatesInfos =  
state.getAdditionalStatesInfos();
```

The state vector could be obtained from a SpacecraftState :

```
final double[] stateVector = new double[]{};  
state.mapStateToArray(OrbitType.CARTESIAN, PositionAngle.MEAN, stateVector);
```

## Transform

The [SpacecraftState](#) class contains methods to compute the following transformations : -

- `toTransform()` or `toTransformForces()` : Transform from orbit/attitude reference frame to spacecraft frame (attitude used for forces computation which is the default attitude).

- `toTransformEvents()` : Transform from orbit/attitude reference frame to spacecraft frame attitude used for events computation (same as `toTransform` if there is no specific attitude for Events).

- `toTransform(Frame)` or `toTransformForces(Frame)` : Transform from specified [Frame](#) to spacecraft frame (attitude used for forces computation which is the default attitude).

- `toTransformEvents(Frame)` : Transform from specified [Frame](#) to spacecraft frame attitude used for events computation (same as `toTransform(Frame)` if there is no attitude specific for Events).

- `toTransform(LOFType)` : Transform from orbit/attitude reference frame to local orbital frame ([LOFType](#)).

- `toTransform(Frame, LOFType)` : Transform from specified [Frame](#) to local orbital frame ([LOFType](#)).

# Getting Started

## Using Transform

Here after is presented the computation of a station position in spacecraft frame:

```
// Station position defined in GCRF
final Vector3D station_InGCRF = new
Vector3D(Constants.EGM96_EARTH_EQUATORIAL_RADIUS, 0, 0);
final Frame gcrf = FramesFactory.getGCRF();
// Compute transform from GCRF to spacecraft frame
final Transform transform = state.toTransform(gcrf);
// Station position in spacecraft frame
final Vector3D station_InSpacecraftFrame =
transform.transformVector(station_InGCRF);
```

Here after is presented the computation of the Sun direction in spacecraft frame.

```
// Compute transform from orbit/attitude reference frame to local orbital
frame TNW
final Transform transform = state.toTransform(LOFType.TNW);
// Position of Sun in local orbital frame TNW
final Vector3D pos =
transform.transformPosition(sun.getPVCoordinates().getPosition());
```

If an [Assembly](#) is used, this is not necessary to use these methods because the conversion methods are included in Assembly functionalities (see [SPC\_VBU\_Home dedicated User Manual]).

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<b>Attitude</b>	Object representing the attitude of the spacecraft for a specific date and in a specific frame. ...	...

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