

# User Manual 4.5 Directions

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## Introduction

### Scope

The "direction" objects are used for attitude computation purposes to describe different types of axis in space that can evolve in time. A direction provides a vector in space at any date in a given frame. A direction can be for example "spacecraft-moon" or "nadir direction of the spacecraft". An attitude law can then be defined using two of those directions.

All available directions belong to the following categories:

- Defined by a "target" moving point, and a given origin point;
- Defined by a vector only known to be constant in time in a particular frame, or defined by a physical property.

The available features are listed in the description of the general `IDirection` interface or of the more specific `ITargetDirection` interface (for directions pointing a target).

### Javadoc

The directions are available in the package `fr.cnes.sirius.patrius.attitudes.directions` of the PATRIUS library.

#### Library

#### Javadoc

Patrius [Package fr.cnes.sirius.patrius.attitudes.directions](#)

### Links

None as of now.

### Useful Documents

None as of now.

### Package Overview

The following diagram represents the two main interfaces of the "directions" package, and for each interface some of the implemented directions. 

## Features Description

### Directions

The available directions are:

## Basic direction

This direction is defined at any date by a vector; this vector can be constant in a frame, or it can be defined by a physical property (for instance the axis of the poles of a celestial body, the orbit momentum, the velocity vector...).

The `getVector` and `getLine` methods of this interface use a `PVCoordinatesProvider` to represent the origin of the direction, but for some of them this input parameter is unused (for instance for the poles of a celestial body direction). See each javadoc for the associated behavior.

All directions can also provide the line containing the given origin and directed by the vector, expressed in any frame of the tree.

## Ground velocity direction

This direction is used for instance when it comes to take pictures of the ground. To avoid distortion, the satellite has to compensate the earth rotation around its yaw axis. On the following drawing, the red direction is the one that has to be followed to compensate the earth rotation.



## Target direction

This direction also implements the methods of basic directions. It is defined at any date by the position of two points of space: the target (that defines the direction) and the origin given by the user. The associated vector (and line) is computed from the origin to the target.

# Getting Started

## Use

### For all directions

All the directions implement the "IDirection" interface and so provide the "getVector" method. This method needs a date and a frame to express the vector, and the PV coordinates of the origin point (unused for some of them). It shall be used this way :

```
Vector3D directionVector = myDirection.getVector(pvCoordinatesProvider, date, frame);
```

They also provide the "getLine" method, with the same arguments.

```
Line directionLine = myDirection.getLine(pvCoordinatesProvider, date, frame);
```

NB : when the `PVCoordinatesProvider` is null then the origin of the direction is tacitly the frame origin.

### For target directions

The directions that implement the "ITargetDirection" interface also provide the "getTarget" method :

```
PVCoordinates directionTarget =  
myTargetDirection.getTargetPVCoordinates(date, frame);
```

## Contents

### Interfaces

Interface	Summary	Javadoc
<b>IDirection</b>	General interface for all directions classes. All basic directions implement it.	<a href="#">...</a>
<b>ITargetDirection</b>	This interface extends IDirection for the particular case of directions defined by a target point. The vector's direction is oriented from the given origin to the target.	<a href="#">...</a>

### Classes

Class	Summary	Javadoc
<b>ConstantVectorDirection</b>	Vector constant in one of the frames of the tree.	<a href="#">...</a>
<b>VelocityDirection</b>	Velocity of the origin point expressed in a reference frame, projected in the given one.	<a href="#">...</a>
<b>MomentumDirection</b>	Momentum : normal vector to the trajectory plane of the origin point around a celestial body.	<a href="#">...</a>
<b>CelestialBodyPolesAxisDirection</b>	Axis of the poles of a celestial body.	<a href="#">...</a>
<b>ToCelestialBodyCenterDirection</b>	Vector from the origin to the center of a celestial body.	<a href="#">...</a>
<b>EarthCenterDirection</b>	Vector from the origin to the center of the Earth central body.	<a href="#">...</a>
<b>GenericTargetDirection</b>	Defined by a PVCoordinatesProvider target.	<a href="#">...</a>
<b>GroundVelocityDirection</b>	Defined by the location of the ground target point given by the pointing direction of the satellite and the body shape.	<a href="#">...</a>
<b>NadirDirection</b>	Defined by the location of the nadir point and the satellite position.	<a href="#">...</a>
<b>CrossProductDirection</b>	Cross Product of two directions.	<a href="#">...</a>
<b>GlintApproximatePointingDirection</b>	Direction to the Sun specular reflexion point.	<a href="#">...</a>
<b>EarthToCelestialBodyCenterDirection</b>	Direction from Earth to the celestial body center.	<a href="#">...</a>

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